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Robot Dynamics - MATLAB & Simulink

Every robot system is created and modified so as to be able to perform the required function. Control systems allow for the movement and function of various parts of the robot, as well as execute a...

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Robot Dynamics - Robotic Systems Lab | ETH Zurich

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Robotics: Science and Systems

The former is useful for simulation, and the latter is useful for robot control. You will also learn how to plan robot trajectories subject to dynamic constraints. This course follows the textbook "Modern Robotics: Mechanics, Planning, and Control" (Lynch and Park,

Cambridge University Press 2017).

Modern Robotics, Course 3: Robot Dynamics | Coursera

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